

# CBM/PHM at Warner Robins ALC

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# Agenda

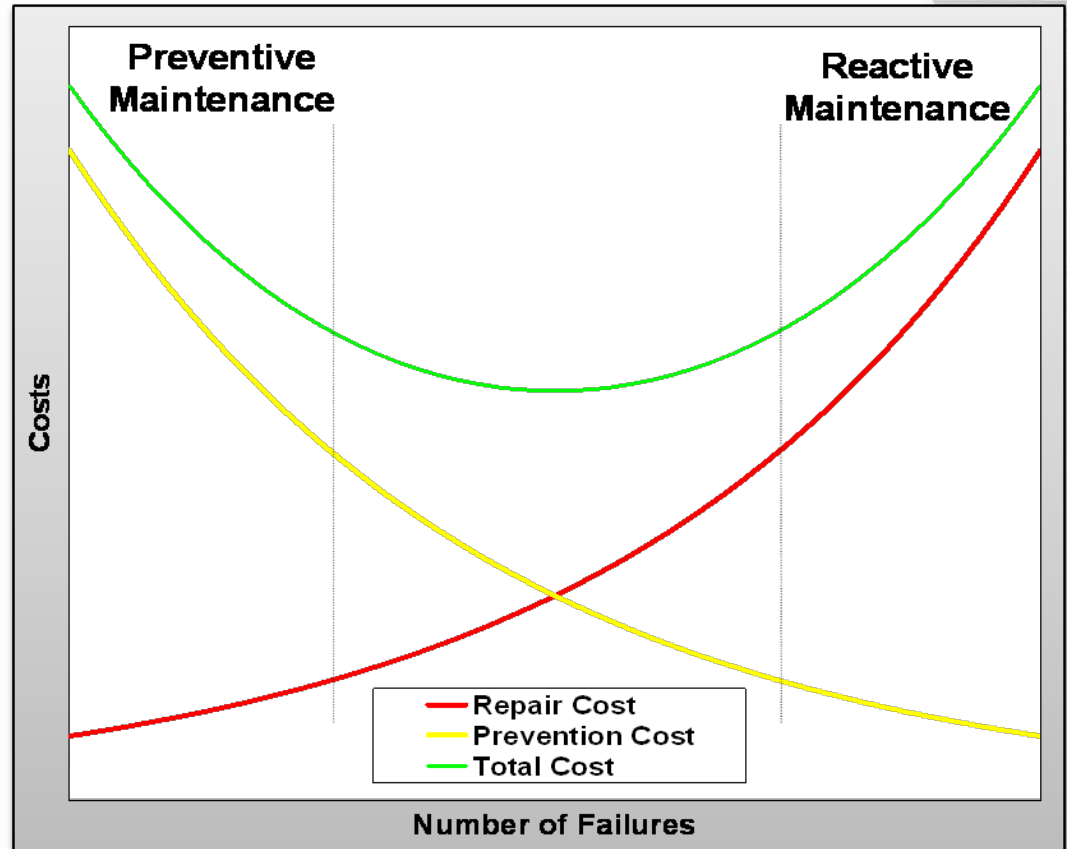
- Background
- The Application Domain: 30V
- Data Acquisition
- Data Analysis
- CBMi Overview
- Benefits
- Lessons Learned
- Going Forward

# Background: Motivation

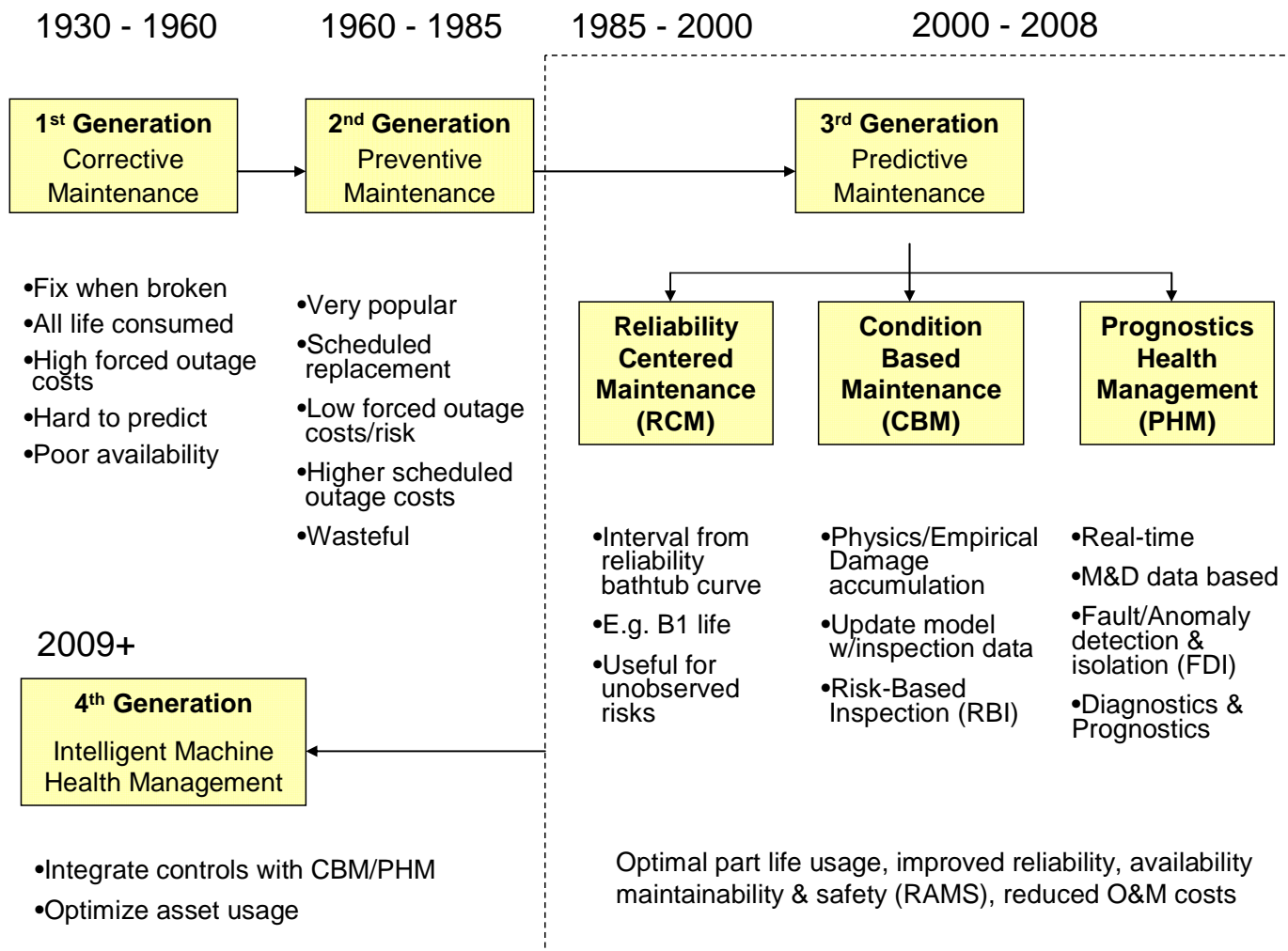
- Department of Defense policy that Condition Based Maintenance (CBM) be implemented to:
  - improve maintenance agility and responsiveness
  - increase operational availability
  - reduce life cycle total ownership costs
- CBM tenets include:
  - need-driven maintenance
  - appropriate use of embedded diagnostics and prognostics through the application of RCM
  - automated maintenance information generation
  - trend based reliability and process improvements
  - integrated information systems providing logistics system response based on equipment maintenance condition

# Background: History

- Purely statistical-based preventative maintenance suffers
  - significant useful life remains in many replaced components
  - limited failures continue to occur in some components prior to scheduled replacement
- Condition-based maintenance and health management
  - reduce maintenance costs
  - increase readiness
  - improve product quality



# Background: Maintenance Strategies



# Background: the Problem

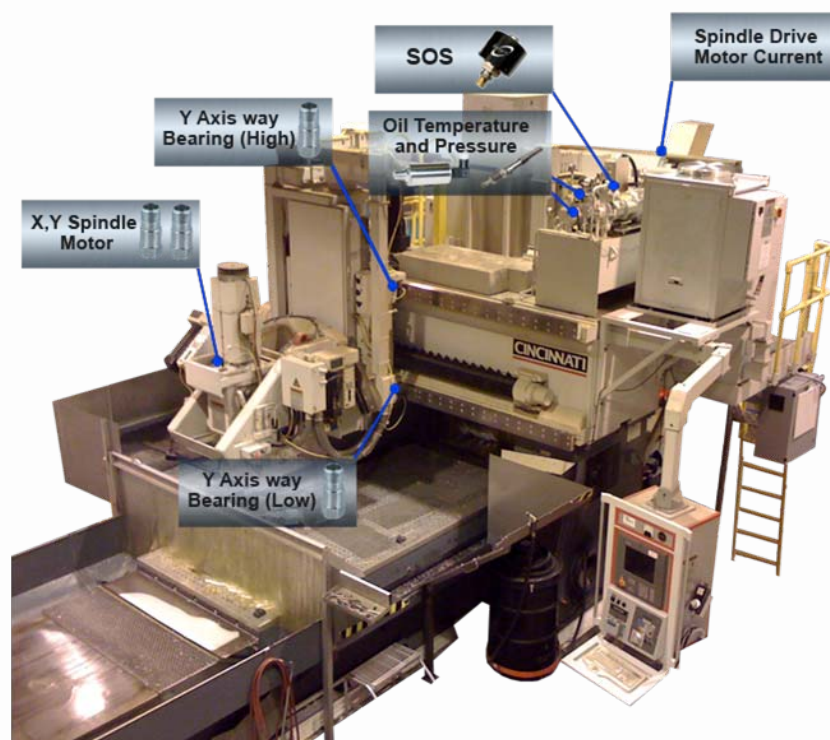
- WR-ALC was looking to transition from a Preventive Maintenance model to a Condition Based Maintenance model.
- Data collection and analysis takes time and experienced personnel.
  - The resources available for analysis are not local
  - Operations personnel are interested in performance indicators
  - Personnel resources are not available to take measurements or analyze the data
- Recent failures on two CNC machines resulted in considerable downtime and cost for critical part replacement.
- In June 2008, it was recommended that these two machines be instrumented and monitored for possible failure modes.

# Background: Goals

- Reduce maintenance cost by 30%
- Improve Reliability, Availability, Maintainability and Safety of ground facilities and air platforms
- Reduce time for repair of aircraft by several days
- Increase uptime of critical ALC facilities to 98%
- Achieve JIT practice in inventoried equipment / supplies / spares
- Optimum utilization of ALC personnel / resources – improve productivity by 10%
- Migrate to CBM practices throughout all ALC operations

# The Application Domain: 30V

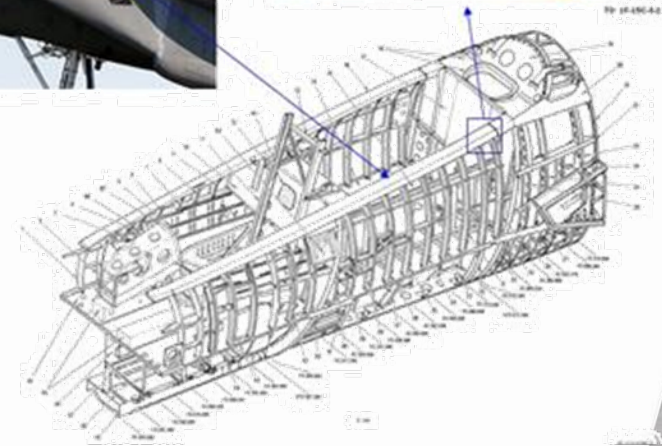
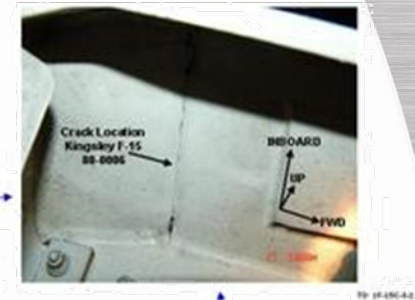
- Located at Robins Air Force Base in Warner Robins, GA
- Critical to Air Force operations, supports:
  - C-5 Galaxy
  - C-17 Globemaster III
  - C-130 Hercules (A, E, H, M variants)
  - E-8 Joint STARS
  - F-15 Eagle
  - HH-60 Pave Hawk
  - MH-53 Pave Low
  - RQ-4 Global Hawk
  - U-2 Dragon Lady
  - UH-1 Iroquois
- 5-axis vertical profiler, 30HP Spindle
- Used to manufacture short runs of critical replacement parts used in USAF aircraft





# The Application Domain: 30V

- Fatigue cracks started by manufacturing defects in a fuselage longeron caused the in-flight break-up of a Boeing F-15C Eagle on 2 November 2007†
- 30V was tasked with replacing these parts in early 2008
- Impact's instrumentation was to transparently implement all sensing without causing any unnecessary downtime or impeding the machine's operations and operators.



Upper longeron location in F-15 forward fuselage

© US Air Force

†Butler, A. (January 10<sup>th</sup> 2008). Manufacturing Defect Root Of F-15C Crash. *AviationWeek*.

# Data Acquisition

- Hardware
  - Transduction TR-5001 PanelPC in NEMA Enclosure

## Acquisition Hardware

- USB-9234 – 4 channel DSA module
  - 51.2 kS/s per-channel maximum sampling rate
  - $\pm 5$  V input, 24-bit resolution
  - 102 dB dynamic range
  - antialiasing filters
- PCI-6023E – 16 channel multifunction DAQ
  - 200 kS/s, 12-bit resolution

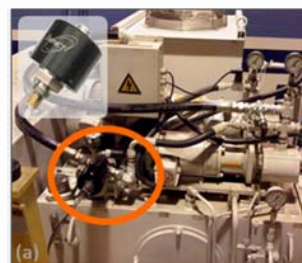
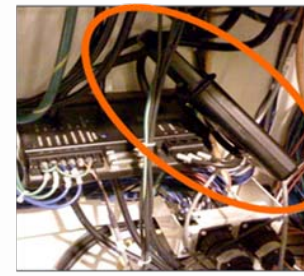
## Sensor/Signal Conditioning Hardware

- 4x Wilcoxon General Purpose Accelerometer
- Impact Technologies SmartMon Oil Quality Sensor
- Amprobe CT-600 AC DC Current Transducer
- Omega OMNI-AMP-IV TC Amplifier with K-type Thermocouple
- Omegadyne PX219-100G10V Pressure Transducer

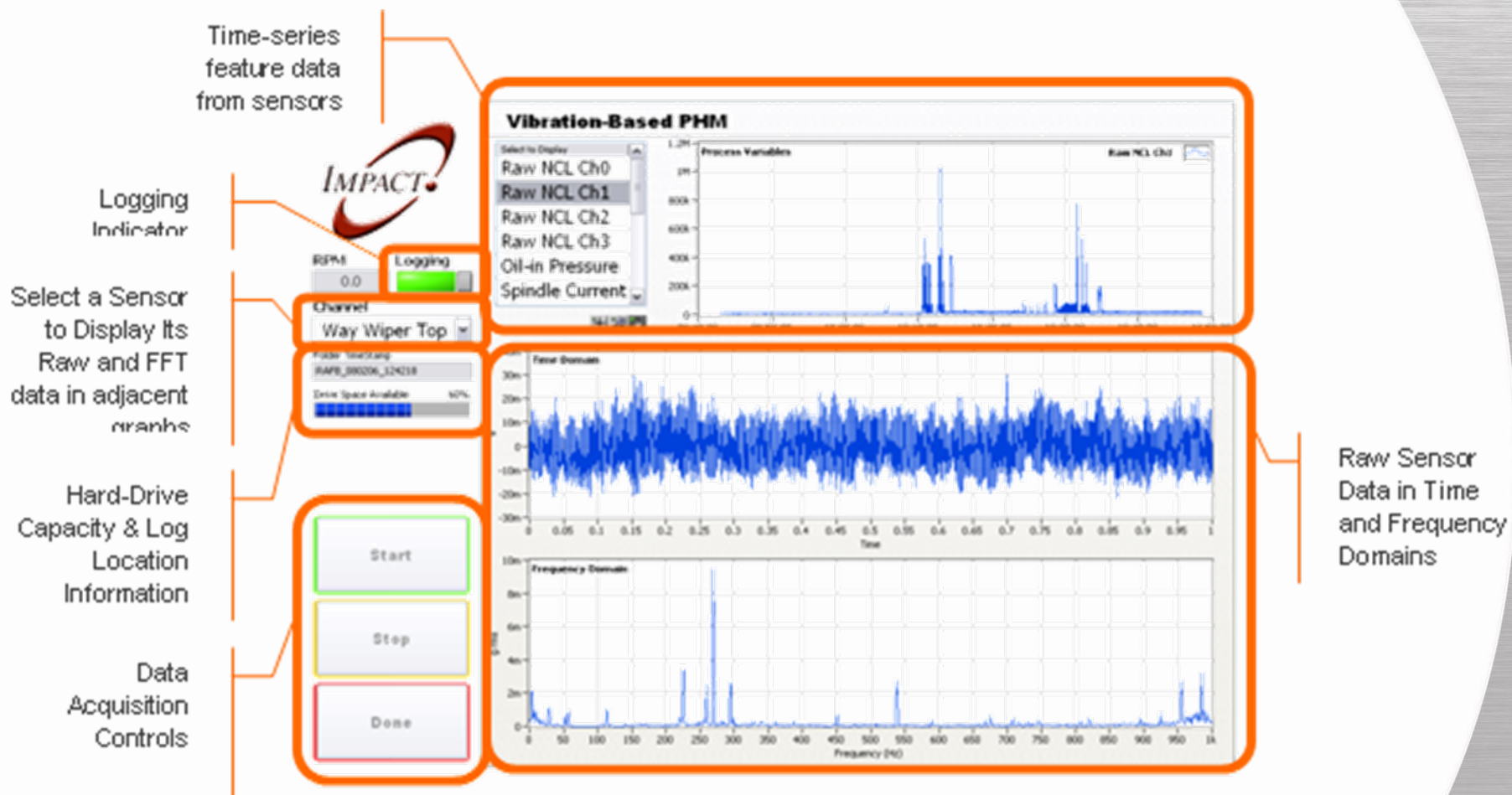


# Data Acquisition

- Axial and Radial Accelerometers Installed on Spindle Motor
- Accelerometers Installed at the Top and Bottom Y-axis Way Bearings
- Current Transducer in Spindle Motor Drive Cabinet
- Impact SmartMon Oil Quality Sensor on the Hydraulic Oil-Return Line
- Temperature and Pressure Transducers on the Hydraulic Oil-In Line



# Data Acquisition Interface



The screenshot displays the IMPACT software interface for data acquisition. It features several key components:

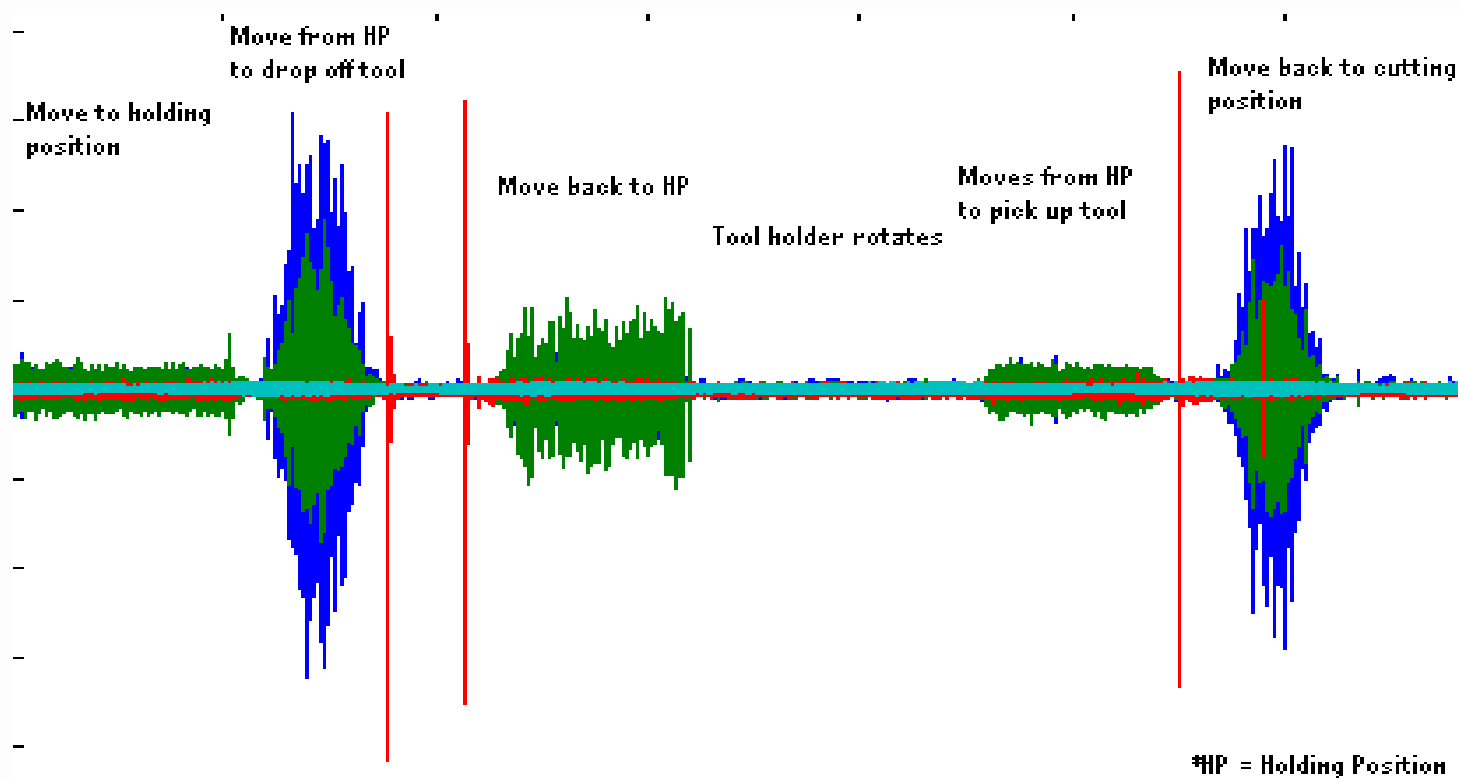
- Logging Indicator:** A green bar indicates that logging is active. RPM is shown as 0.0.
- Sensor Selection:** A dropdown menu is set to "Way Wiper Top".
- Drive Space:** A progress bar shows 40% drive space available.
- Acquisition Controls:** Three buttons labeled "Start", "Stop", and "Done" are visible.
- Vibration-Based PHM Panel:**
  - Select to Display:** A list includes Raw NCL Ch0, Raw NCL Ch1 (selected), Raw NCL Ch2, Raw NCL Ch3, Oil-in Pressure, and Spindle Current.
  - Process Variables:** A time-series plot showing amplitude over time.
- Raw Sensor Data:** Two plots are shown:
  - Time Domain:** A plot of amplitude vs. Time (0 to 1).
  - Frequency Domain:** A plot of amplitude vs. Frequency (0 to 1k Hz).

Annotations on the left side of the interface identify these sections:

- Time-series feature data from sensors:** Points to the PHM and Process Variables plots.
- Logging Indicator:** Points to the RPM and Logging status.
- Select a Sensor to Display its Raw and FFT data in adjacent graphs:** Points to the sensor selection dropdown.
- Hard-Drive Capacity & Log Location Information:** Points to the drive space progress bar.
- Data Acquisition Controls:** Points to the Start, Stop, and Done buttons.
- Raw Sensor Data in Time and Frequency Domains:** Points to the Time and Frequency Domain plots.

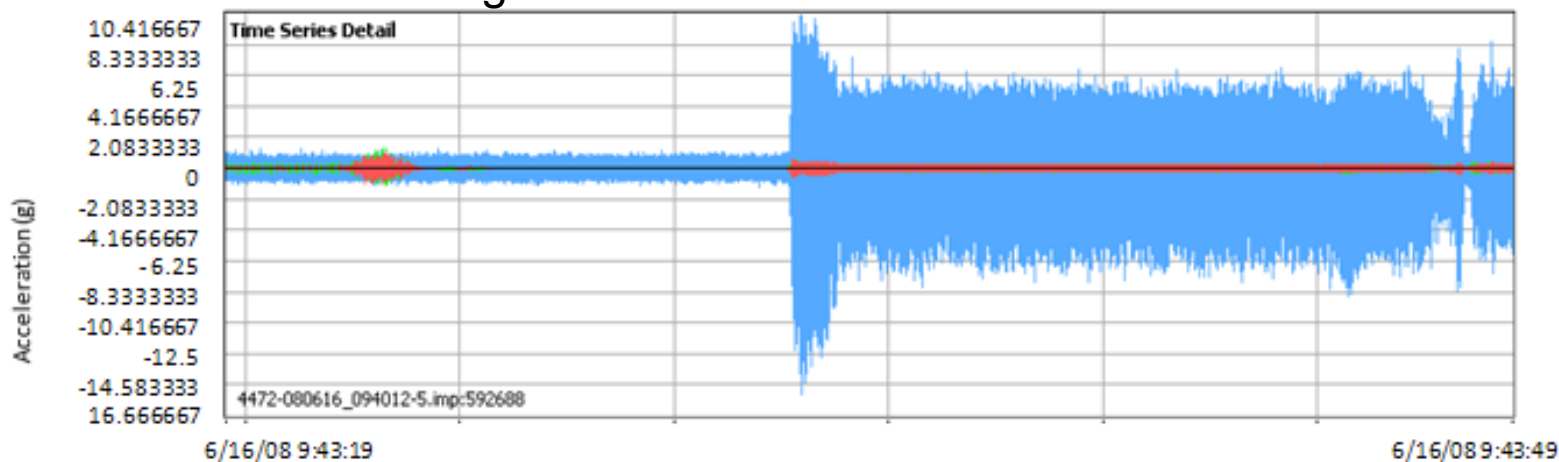
# Data Analysis

## Tool Change Event – Sequence of Vibration Signatures in Spindle and Way Bearings Accelerometers

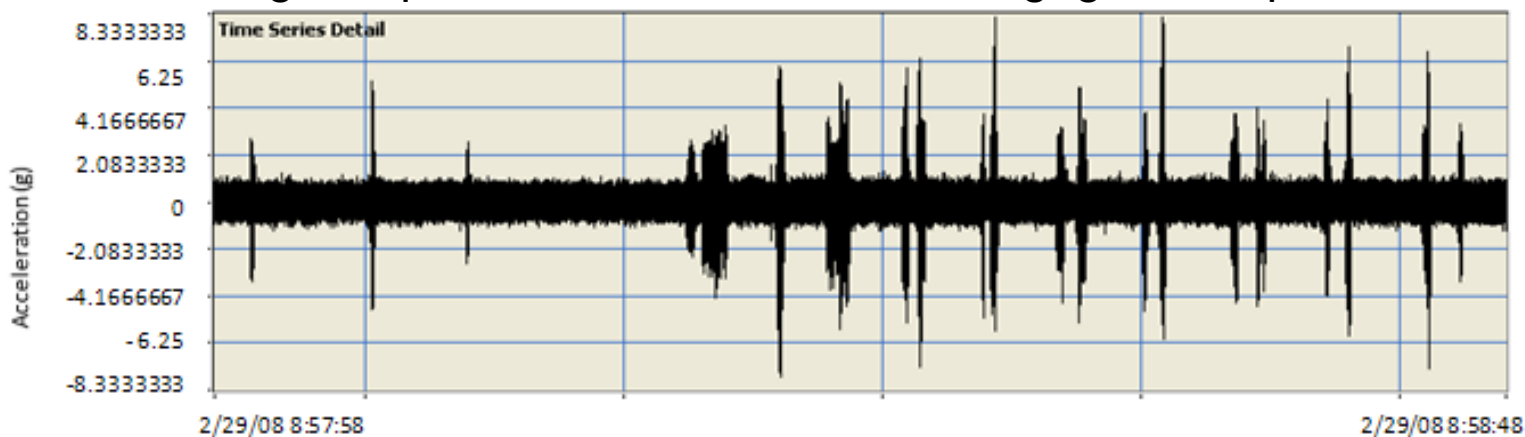


# Data Analysis

## Tool breakage

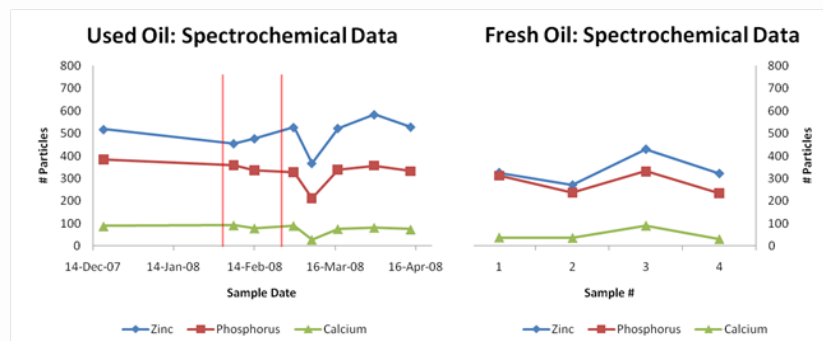
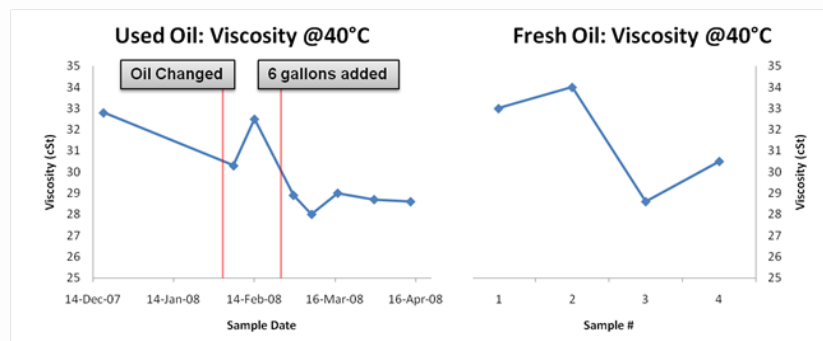
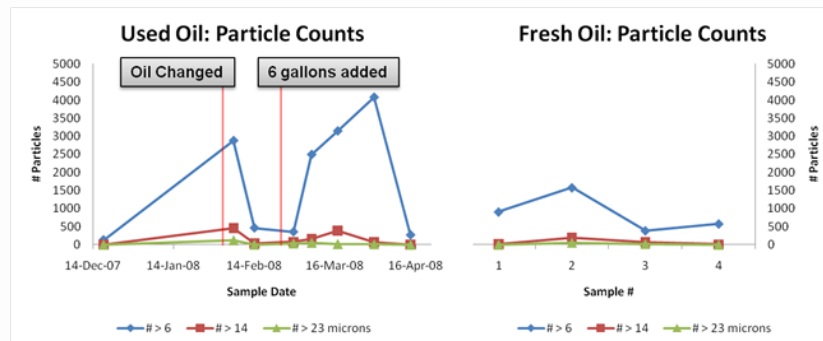
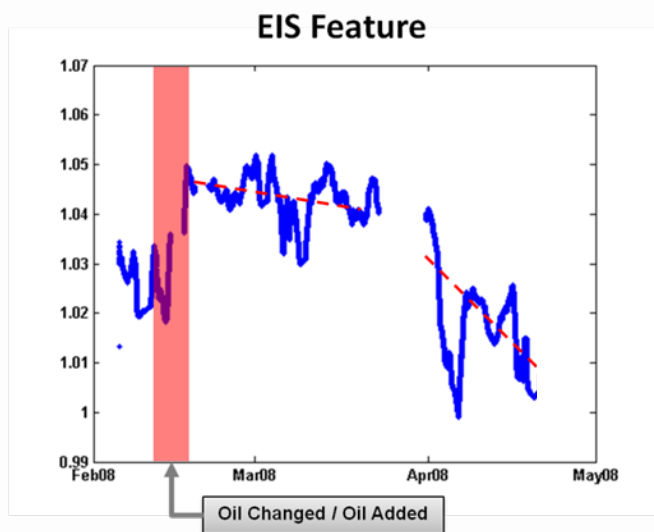


## High amplitude vibration when tool engaged with part



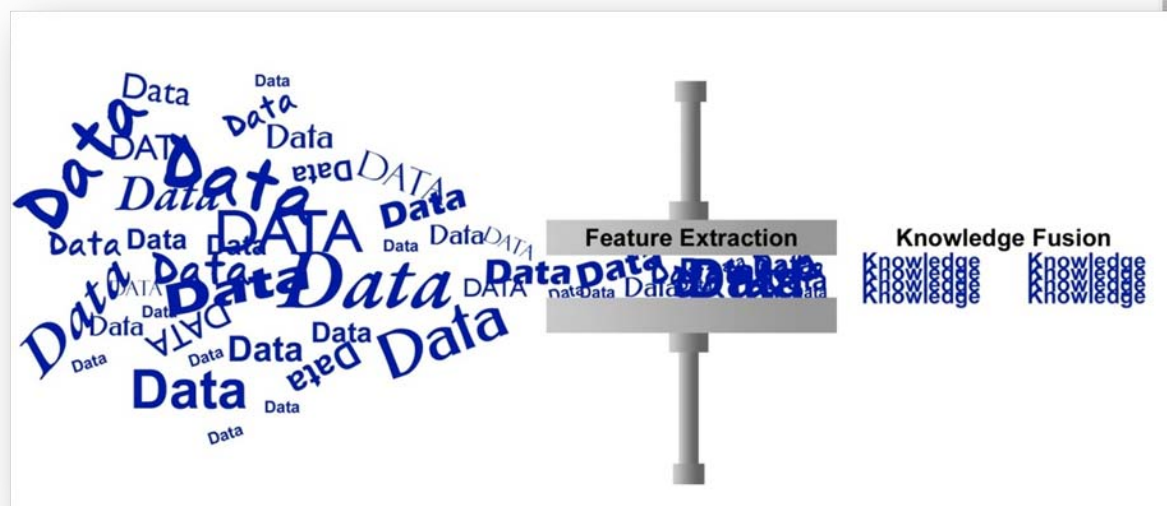
# Data Analysis

- The sensor “feature” data appears to show some sensitivity to the oil change, and also appears to generally have a downward trend over time.



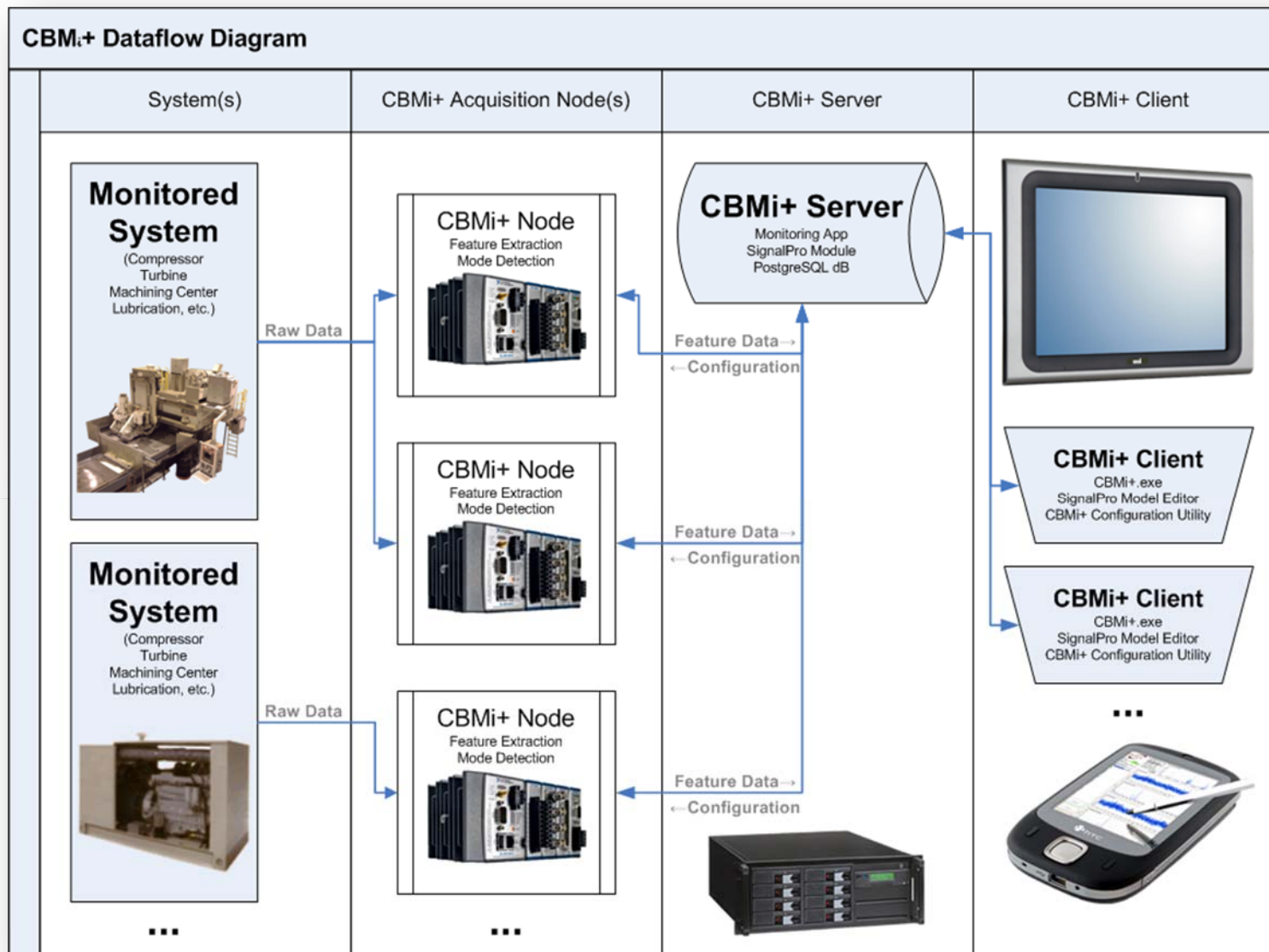
# a Solution – CBMi

- Automatically collects, processes, and posts relevant information to a central repository.
- Information is available remotely to all interested users.
- Automatic alarms and notifications based on customizable inference systems, or simple threshold crossings.
- Scales from a single asset, to an entire facility.





# CBMi Data Flow Diagram



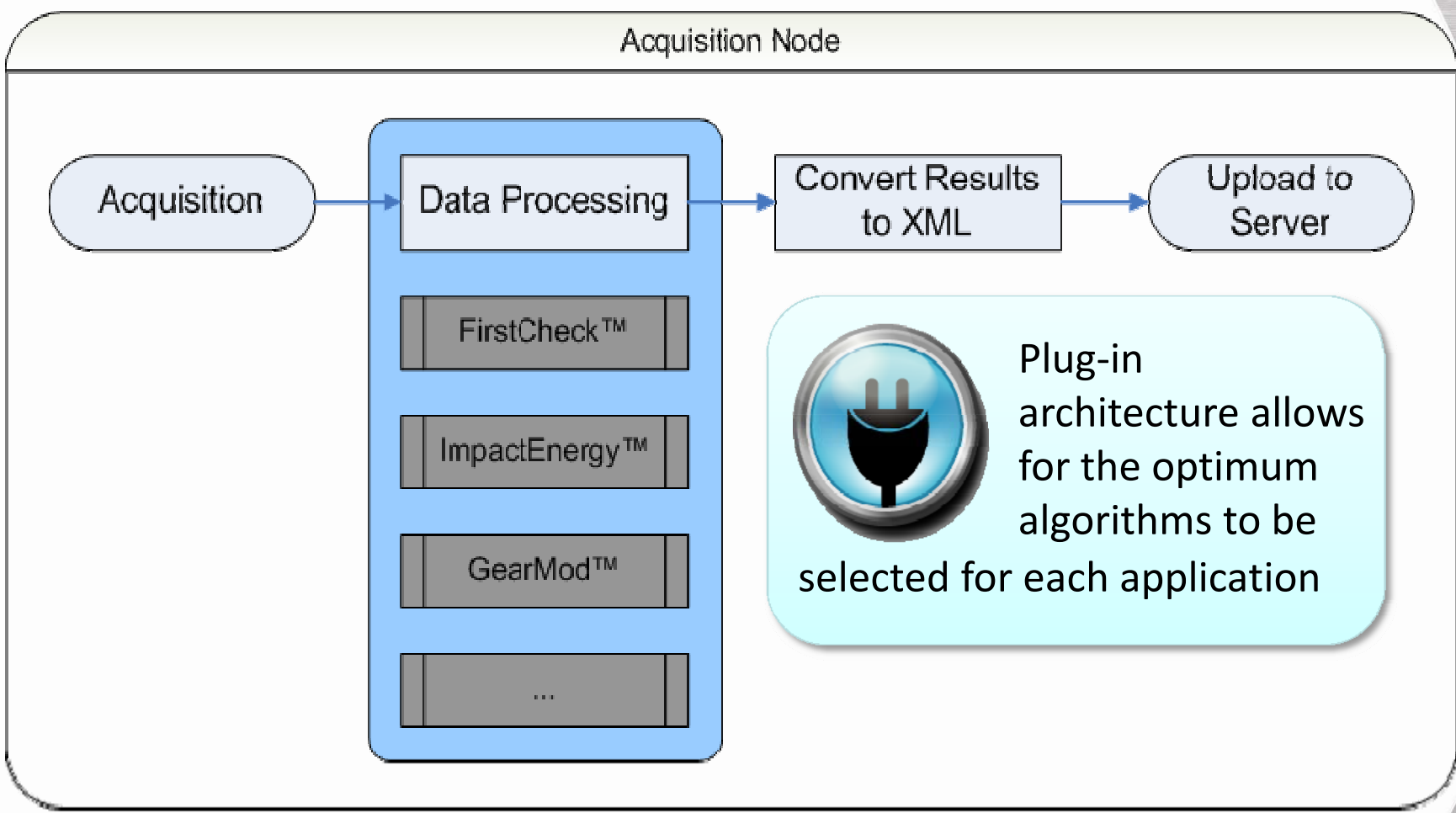
# Hardware

## Acquisition Node Flexibility

- A variety of 1<sup>st</sup> and 3<sup>rd</sup> party devices are available as acquisition nodes

Device	Cost	Expansion Options	Flexibility	Processing Power	Size	Required Power	Robustness
 <b>NI PXI Platform</b>	Red	Green	Green	Green	Red	Red	Red
 <b>NI Compact RIO</b>	Yellow	Green	Green	Yellow	Yellow	Yellow	Green
 <b>Impact-RLW S2NAP</b>	Green	Yellow	Yellow	Red	Yellow	Yellow	Green
 <b>Impact-RLW S5NAP</b>	Green	Red	Red	Red	Green	Green	Green

# Acquisition Node Responsibilities



# National Instruments CompactRIO



- Small, rugged embedded control and data acquisition system
- Embedded real-time processor for reliable stand-alone operation
- Hot-swappable industrial I/O modules with built in signal conditioning
- Extreme industrial certifications:
  - -40 to 70 °C (-40 to 158 °F) operating temperature
  - Up to 2,300 Vrms isolation (withstand)
  - 50 g shock rating
  - International safety, EMC, and environmental certifications
  - Class I, Division 2 rating for hazardous locations

# Software

## CBMi with SignalPRO

- A widely applicable, data-driven, automated fault detection system for performance & condition monitoring
- Key Concepts:
  - Easy to install / use / maintain
  - Generic Models
    - Models based on existing data → no specialized application specific equations
    - Point & Click interface to build and maintain models
  - Continuous / on-line anomaly detection (“continuous commissioning”)
  - Remote access to diagnostic information
- Combination of CBMi and SignalPRO increases potential application areas
  - Both performance and true condition monitoring

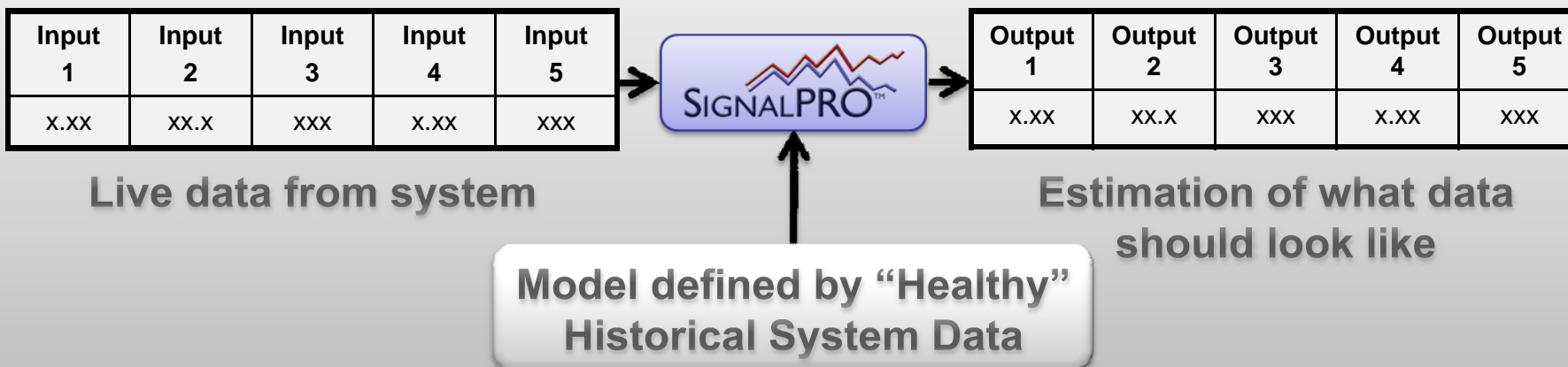
# SignalPRO Model

- Multiple ‘snapshots’ in time to characterize the behavior of the system
  - Think of a spreadsheet – columns are sensors, rows are data from different operating points and points in time.
- Can be
  - Historical data
  - Initial installation data
  - Data from models: (e.g. thermal performance codes)
- Best if
  - Covers entire expected range of (healthy) operation
  - Low in random noise
  - All data is related (monitors same process)

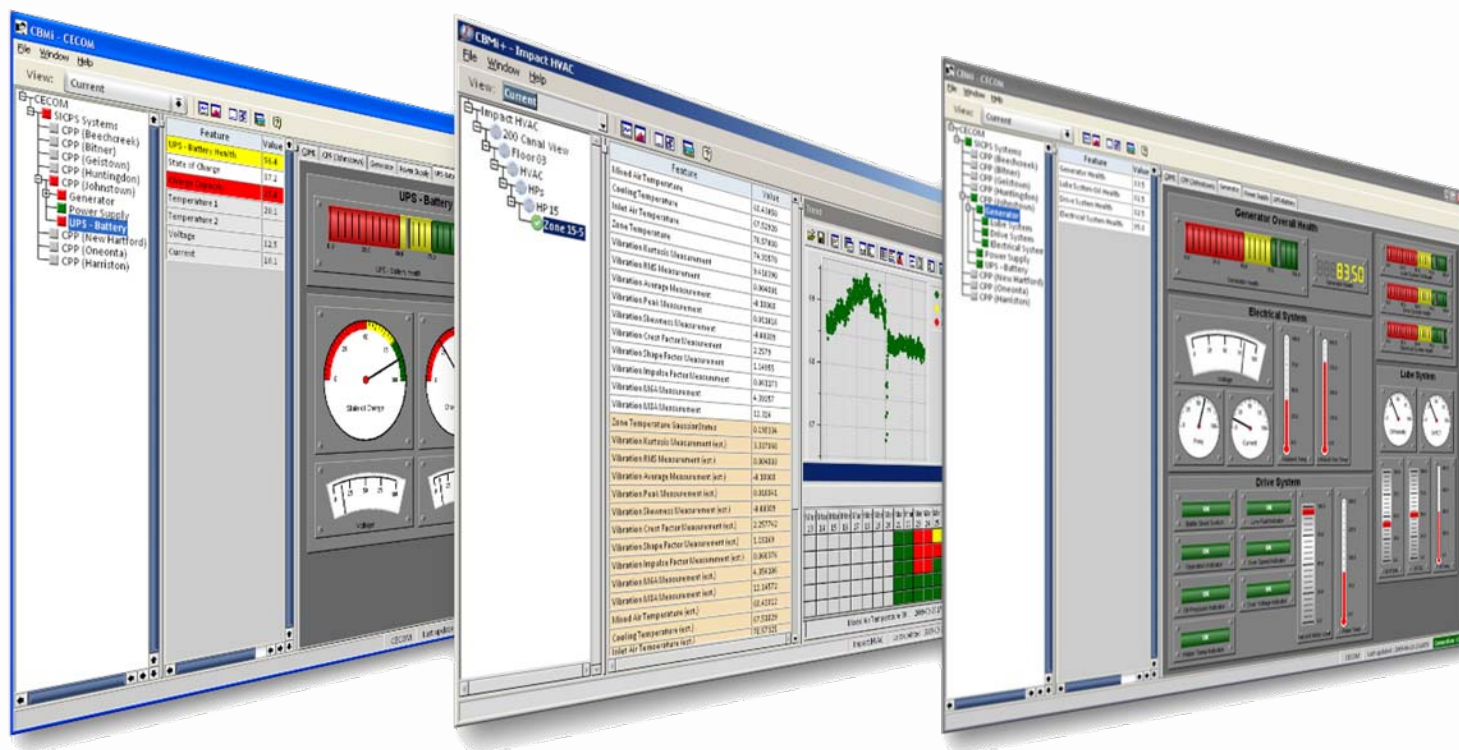
# SignalPRO Engine

## Anomaly Detection

- Data driven system modeling engine
  - Transfer function uses “Similarity techniques”
- Input: Current vector of data & the model
  - Sensor or calculated data (e.g. efficiency)
- Output: Estimated values of the input data, assuming a healthy system.
  - A single point in time



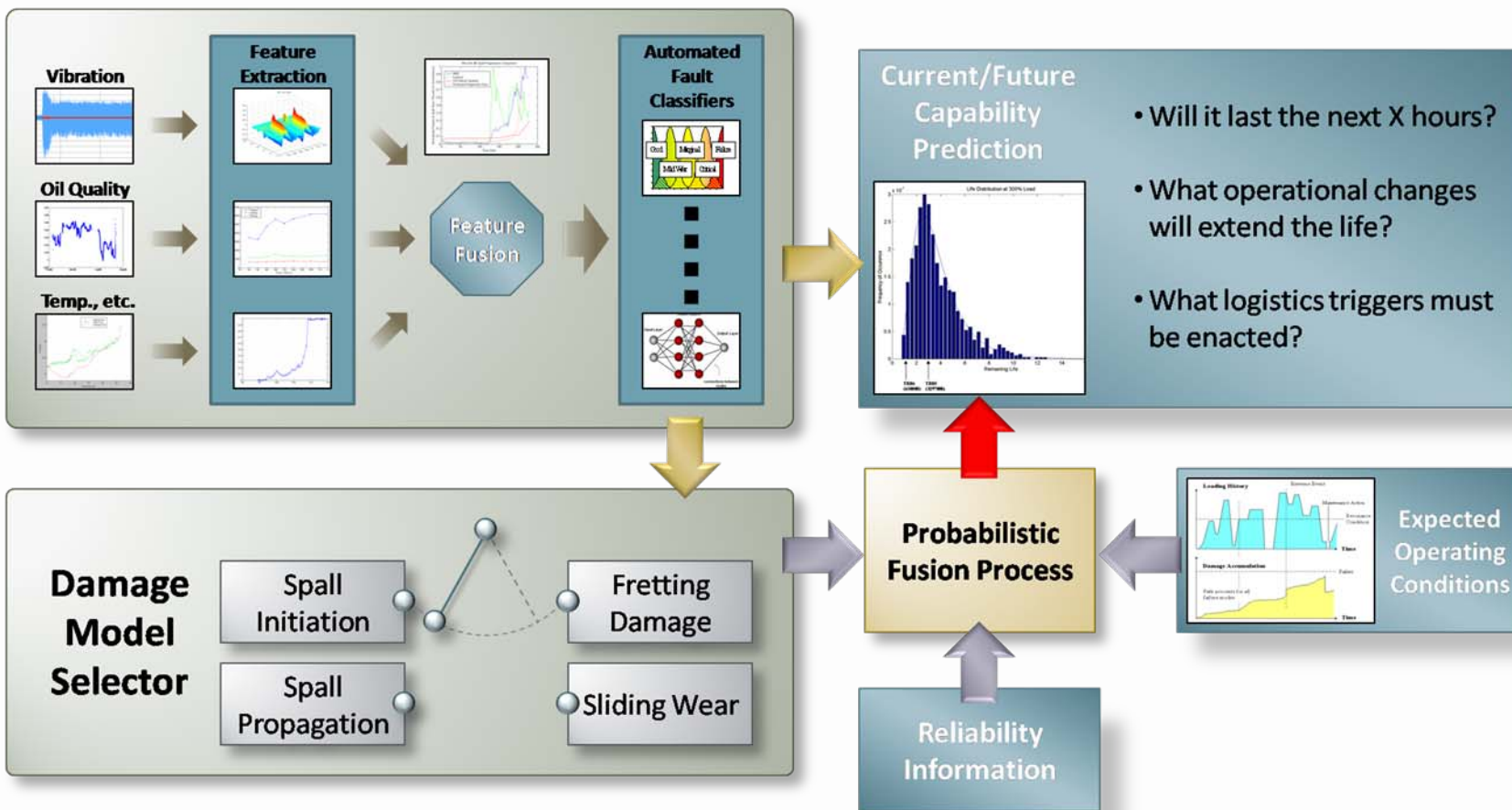
# CBMi Client Interface



Drill-downs  
 Roll-ups  
 Plant  
 Equipment  
 Sensor



# General Approach to Model-Based Prognostics



# Potential Benefits

- Continuous online health monitoring and assessment
- Optimum maintenance overhaul/repair schedules (for spare parts/personnel/ facilities/tools etc)
- Maintenance cost reduction
- Improvement of equipment reliability/safety (avoid catastrophic failures)
- Optimum planning schedules for equipment and facilities for specific missions
- Reduce Unjustified Repair/Removal rates and Increase Justified rates
- Reduced Can Not Duplicate (CND) rates
- Reduced maintenance induced failures
- Reduced numbers of tests to isolate failures
- Reduced repair times (enhanced availability)

# 30V Machining Center CBM Implementation Results

- Reduced shop maintenance cost of systems monitored to near zero
- *Increased uptime of 30V Machining Center by 80 Hours*
- Improved equipment reliability/safety (avoided any catastrophic failures)
- Enhanced optimum planning schedules for equipment for specific F-15 missions enhanced availability
- Reduce Unjustified Repair/Removal rates
- Reduced maintenance induced failures
- Continuous online health monitoring and assessment

# Lessons Learned

- In general, equipment operators should be included in the planning early so that they understand that the monitoring system is designed to monitor the equipment, not them, and it should make their jobs easier.
- A non-real-time (NRT) operating system like Windows XP is not ideal when consistent power may not be available, even when a UPS is utilized to mitigate problems.
- Lack of key parameters such as operating speed and cycle definitions can be overcome with intelligent algorithm development.
- An industrial grade wireless modem can reliably provide network access when local infrastructure is not available, even in a manufacturing environment where large metallic structures and high current power lines are present.
- Extended periods of continuous monitoring may be required before the data required for fault isolation algorithm development is provided, particularly from a machine which is typically reliable.
- High quality 50' accelerometer cables and superior signal conditioning kept electromagnetic noise from becoming an issue, even though the cabling was run in parallel to the motor drive lines.

# Going Forward

- Implement CBMi at WR-ALC
- Fully integrate the general approach to model-based prognostics with CBMi so that it can be leveraged at WR
- Apply advanced algorithms:
  - FirstCheck: sensor validation
  - ImpactEnergy & IE FIS: bearing incipient fault detection
  - GearMod: drivetrain and gearbox diagnostics
- Expand sensing to more machines
- Target problem areas instead of reliable machines to fully realize the ROI